

POZNAN UNIVERSITY OF TECHNOLOGY

EUROPEAN CREDIT TRANSFER AND ACCUMULATION SYSTEM (ECTS)

COURSE DESCRIPTION CARD - SYLLABUS

Course name

Devices of automation and actuators [S1AiR1E>EiUA]

Course

Field of study Year/Semester

Automatic Control and Robotics 3/5

Area of study (specialization) Profile of study

general academic

Level of study Course offered in

first-cycle English

Form of study Requirements full-time compulsory

Number of hours

Lecture Laboratory classes Other (e.g. online)

30 0

Tutorials Projects/seminars

0 0

Number of credit points

5,00

Coordinators Lecturers

dr inż. Stanisław Gardecki stanislaw.gardecki@put.poznan.pl

Prerequisites

none

Course objective

none

Course-related learning outcomes

Knowledge:

Has a basic knowledge of metrology, knows and understands the methods of measurement of electrical and non-electrical quantities; knows the computational methods and computer tools necessary to analyse experimental results [K1 W11 (P6S WG)].

Has advanced structured knowledge in the construction, application and control of automation and robotics executive systems [K1_W18 (P6S_WG)].

Knows and understands typical engineering technologies, principles and techniques of construction of simple automation and robotics systems; knows and understands the principles of selection of executive systems, computational units and measurement and control elements and devices [K1_W20 (P6S_WG)]. Knows and understands the basic processes in the life cycle of devices and selected safety systems used

in automation and robotics [K1_W22 (P6S_WG)]. Skills:

Can interpret with understanding the design technical documentation and simple technological diagrams of automation and robotics systems [K1 U2 (P6S UW)].

Can determine and use models of simple electromechanical systems and selected industrial processes, and use them for analysis and design of automation and robotics systems [K1_U11 (P6S_UW)]. Be able to use appropriately selected methods and measuring instruments and measure relevant signals

and, on the basis of these, determine the static and dynamic characteristics of automation components and obtain information on their basic properties [K1 U14 (P6S UW)].

Is able to build, commission and test a simple electronic and electromechanical system [K1_U15 (P6S_UW)].

Social competences:

The graduate is aware of the need for a professional approach to technical issues, meticulous familiarization with the documentation and environmental conditions in which the equipment and its components can operate. The graduate is ready to observe the rules of professional ethics and to demand it from others, to respect the diversity of opinions and cultures [K1 K5 (P6S KR)].

Methods for verifying learning outcomes and assessment criteria

Learning outcomes presented above are verified as follows:

none

Programme content

none

Course topics

none

Teaching methods

none

Bibliography

none

Breakdown of average student's workload

| | Hours | ECTS |
|--|-------|------|
| Total workload | 120 | 5,00 |
| Classes requiring direct contact with the teacher | 60 | 2,50 |
| Student's own work (literature studies, preparation for laboratory classes/tutorials, preparation for tests/exam, project preparation) | 60 | 2,50 |